



Lower-Stretch Spanning Trees

Presenter: Yajun Wang

Introduction

- Graph Embedding on Tree Metrics

Average $O(\log^2 n \log \log n)$ stretch.

$$\text{stretch}_T(u, v) = \frac{\text{dist}_T(u, v)}{d(u, v)}$$

$$\text{ave-stretch}_T(E) = \frac{1}{|E|} \sum_{(u, v) \in E} \text{stretch}_T(u, v)$$

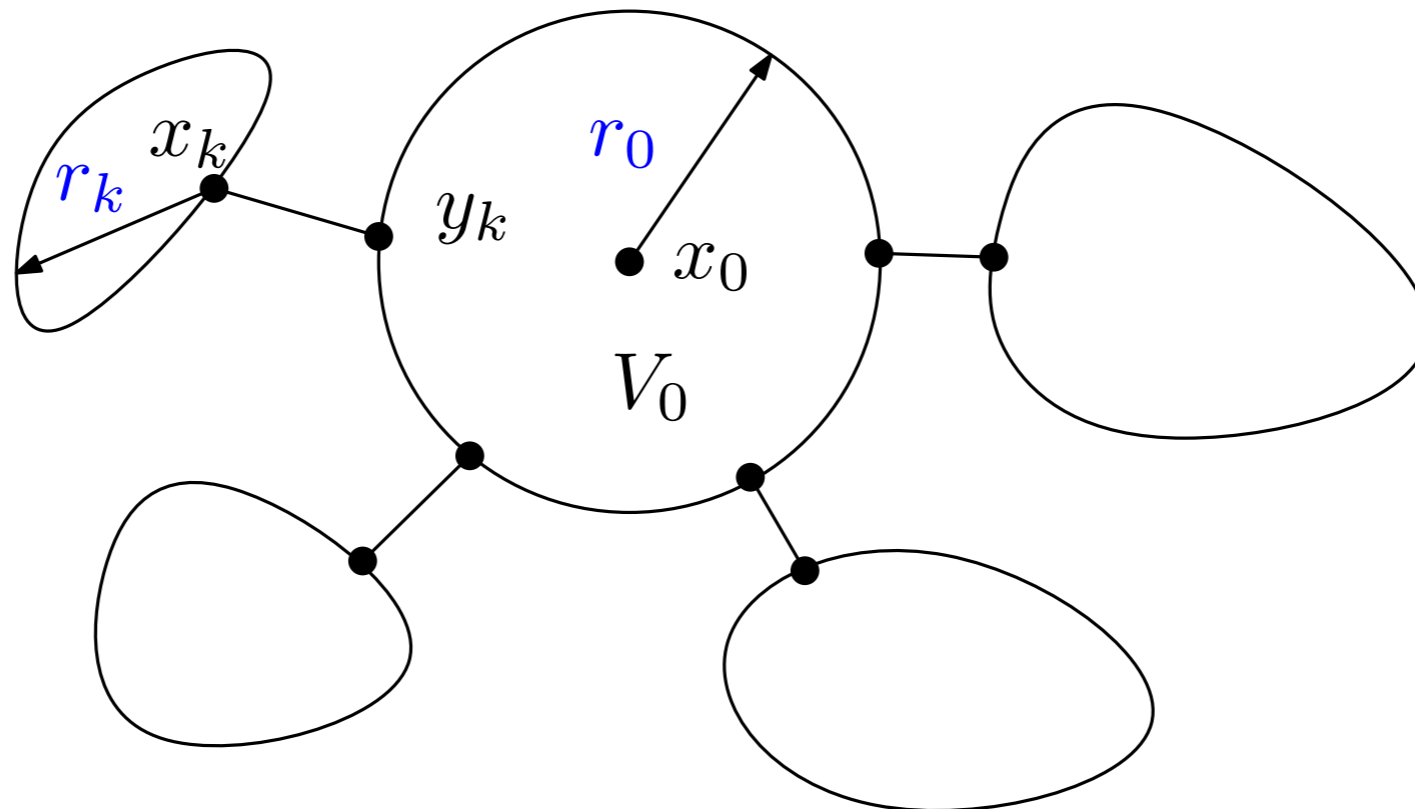
- Star Decomposition

Notation

- The *boundary* of S , ∂S : the set of edges with exactly one endpoint in S .
- The *volumn* of a set of edges F , $\text{vol}(F)$: the size of the set F .
- The *volumn* of a set of vertices S , $\text{vol}(S)$: the number of edges incident to S .
- The *ball shell* around a vertex v , $\text{BS}(r, v)$: the set of vertices "right" outside $B(r, v)$.
- The *cost* (weight) of an edge, the length is $d(e) = 1/w(e)$.

Low-Cost Star-Decomposition

- A multiway partition $\{V_0, V_1, \dots, V_k\}$ with center $x_0 \in V_0$ is a *star-decomposition*:
 - subgraphs induced by V_i are connected.
 - $x_i \in V_i$ is connected to a vertex $y_i \in V_0$ by an edge $(x_i, y_i) \in E$. (*bridge*).



Low-Cost Star-Decomposition

- ▣ Let $r = \text{rad}_G(x_0)$, and $r_i = \text{rad}_{V_i}(x_i)$. For $\delta, \epsilon \leq 1/2$, a star-decomposition is a (δ, ϵ) -star-decomposition if
 - ▣ $\delta r \leq r_0 \leq (1 - \delta)r$
 - ▣ $r_0 + d(x_i, y_i) + r_i \leq (1 + \epsilon)r$
- ▣ The *cost* of the star-decomposition is $\text{cost}(\partial(V_0, V_1, \dots, V_k))$, the sum of cost of the edges between the sets.

Low-Cost Star-Decomposition

- Let $G = (V, E, w)$ be a connected weighted graph and $x_0 \in V$. For every positive $\epsilon \leq 1/2$,

$$(\{V_0, V_1, \dots, V_k\}, \mathbf{x}, \mathbf{y}) = \text{starDecomp}(\mathbf{G}, \mathbf{x}_0, \mathbf{1/3}, \epsilon),$$

in time $O(m + n \log n)$, returns a $(1/3, \epsilon)$ -star-decomposition of G with center x_0 of cost

$$\text{cost}(\partial(V_0, V_1, \dots, V_k)) \leq \frac{6m \log_2(m + 1)}{\epsilon \cdot \text{rad}_G(x_0)}$$

- $\delta r \leq r_0 \leq (1 - \delta)r$
- $r_0 + d(x_i, y_i) + r_i \leq (1 + \epsilon)r$

$O(\log^3 m)$ Average Stretch Tree

Algorithm for Unweighted Graphs

Fix $\alpha = (2 \log_{4/3}(\hat{n} + 6))^{-1}$.

$T = \text{UnweightedLowStretchTree}(G, x_0)$

1. If $|V| \leq 2$, return G .
2. Set $\rho = \text{rad}_G(x_0)$
3. $(\{V_0, V_1, \dots, V_k\}, \mathbf{x}, \mathbf{y}) = \text{StarDecomp}(\mathbf{G}, \mathbf{x}_0, \mathbf{1}/\mathbf{3}, \alpha)$
4. For each i ,
set $T_i = \text{UnweightedLowStretchTree}(G(V_i), x_i)$.
5. Set $T = \cup_i T_i \cup_i (y_i, x_i)$.

$O(\log^3 m)$ Average Stretch Tree

□ Analysis

Depth of recursion: $O(\log_{4/3} n)$

$$\text{rad}_{R_t(G)}(x_0) \leq (1 + \alpha)^t \text{rad}_G(x_0) \leq \sqrt{e} \cdot \text{rad}_G(x_0).$$

$$\begin{aligned} \sum_{(u,v) \in \partial(V_0, \dots, V_k)} \text{stretch}_T(u, v) &\leq \sum_{(u,v) \in \partial(V_0, \dots, V_k)} (\text{dist}_T(x_0, u) + \text{dist}_T(x_0, v)) \\ &\leq \sum_{(u,v) \in \partial(V_0, \dots, V_k)} 2\sqrt{e} \cdot \text{rad}_G(x_0) \\ &\leq 2\sqrt{e} \cdot \text{rad}_G(x_0) \frac{6m \log_2(\hat{m} + 1)}{\alpha \cdot \text{rad}_G(x_0)} \end{aligned}$$

$$\sum_{(u,v) \in E} \text{stretch}_T(u, v) = O(\hat{m} \log^3 \hat{m}).$$

$O(\log^3 m)$ Average Stretch Tree

Algorithm for Weighted Graphs

Fix $\beta = (2 \log_{4/3}(\hat{n} + 32))^{-1}$. $T = \text{LowStretchTree}(G, x_0)$

1. If $|V| \leq 2$, return G .
2. Set $\rho = \text{rad}_G(x_0)$
3. Let $\tilde{G} = (\tilde{V}, \tilde{E})$ be the graph by contracting all edges in G with length less than $\beta\rho/\hat{n}$.
4. $(\{\tilde{V}_0, \dots, \tilde{V}_k\}, \mathbf{x}, \mathbf{y}) = \text{StarDecomp}(\tilde{G}, \mathbf{x}_0, \mathbf{1}/\mathbf{3}, \beta)$
5. For each i , let V_i be the preimage of \tilde{V}_i , and (x_i, y_i) be one of the preimage of $(\tilde{x}_i, \tilde{y}_i)$.
6. For each i ,
set $T_i = \text{LowStretchTree}(G(V_i), x_i)$.
7. Set $T = \cup_i T_i \cup_i (y_i, x_i)$.

$O(\log^3 m)$ Average Stretch Tree

□ Analysis

Let $t = 2 \log_{4/3}(\hat{n} + 32)$ and $\rho_t = \text{rad}_{R_t(G)}(x_0)$

$$\rho_t \leq \sqrt{e} \cdot \text{rad}_G(x_0)$$

Each component has radius at most $\rho(3/4)^t \leq \rho/n^2..$

Each edge appears at most $\log_{4/3}((2\hat{n}/\beta) + 1)$ recursion depths.

The total contribution to the stretch at level t is

$$O(\text{vol}(E_t) \log^2 \hat{m})$$

Star Decomposition

▣ Concentric System

A family of vertex sets $\mathcal{L} = \{L_r \subseteq V : r \in \mathbb{R}^+ \cup \{0\}\}$.

1. $L_0 \neq \emptyset$,
2. $L_r \subseteq L_{r'}$ for all $r \leq r'$,
3. if a vertex $u \in L_r$ and $(u, v) \in E$, then $v \in L_{r+d(u,v)}$.

Star Decomposition

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3. if a vertex $u \in L_r$ and $(u, v) \in E$, then $v \in L_{r+d(u,v)}$.

▣ Property: For every two reals $0 \leq \lambda \leq \lambda'$, there exists a real $r \in [\lambda, \lambda')$ such that

$$\text{cost}(\partial(L_r)) \leq \frac{\text{vol}(L_r)}{\lambda' - \lambda} \max \left[1, \log_2 \left(\frac{m}{\text{vol}(E(L_r))} \right) \right]$$

Star Decomposition

- Proof of the property:

$$\text{cost}(\partial(L_r)) \leq \frac{\text{vol}(L_r)}{\lambda' - \lambda} \max \left[1, \log_2 \left(\frac{m}{\text{vol}(E(L_r))} \right) \right]$$

Sort the vertices according to the distances to the center.

$$\text{Let } \mu_i = \text{vol}(E(B_i)) + \sum_{(v_j, v_k) \in E: j \leq i < k} \frac{r_i - r_j}{r_k - r_j}.$$

$$\mu_{i+1} = \mu_i + \text{cost}(\partial(B_i))(r_{i+1} - r_i)$$

$$\text{Let } r_{a-1} \leq \lambda < \lambda' \leq r_{b+1}, \text{ and } \eta = \log_2 \left(\frac{m}{\text{vol}(E(B_{a-1}))} \right)$$

Prove there exists $i \in [a - 1, b]$ such that

$$\text{cost}(\partial(B_i)) \leq \mu_i \eta / (\lambda' - \lambda).$$

Star Decomposition

□ $r = \text{BallCut}(G, x_0, \rho, \delta)$

1. Set $r = \delta\rho$

2. While $\text{cost}(\partial(B(r, x_0))) > \frac{\text{vol}(B(r, x_0)) + 1}{(1 - 2\delta)\rho} \log_2(m + 1)$,
Find the next vertex v and set $r = \text{dist}(x_0, v)$.

□ Result:

$$\rho/3 \leq r \leq 2\rho/3$$

$$\text{cost}(\partial(V_0)) > \frac{3(\text{vol}(V_0) + 1) \log_2(|E| + 1)}{\rho}$$

Star Decomposition

- ▣ Ideals and Cones

For set $S \subseteq V$,

$$F(S) = \{(u \rightarrow v) : (u, v) \in E, \text{dist}(u, S) + d(u, v) = \text{dist}(v, S)\}$$

- ▣ The *ideal* of v , $I_S(v)$, induced by S , is the set of vertices that reachable from v in $F(S)$
- ▣ The *cone* of width l around v induced by S , $C_S(l, v)$, is the set of vertices in V that can be reached from v by a path, the sum of lengths of whose edges not in $F(S)$ is at most l .

Star Decomposition

- Cones are concentric

$$r = \text{ConeCut}(G, v, \lambda, \lambda', S)$$

- Set $r = \lambda$ if $\text{vol}(E(C_S(\lambda, v))) = 0$,
Set $\mu = (\text{vol}(C_S(r, v)) + 1) \log_2(m + 1)$.
otherwise,
Set $\mu = \text{vol}(C_S(r, v)) \log_2(m / \text{vol}(E(C_S(\lambda, v))))$.
- While $\text{cost}(\partial(C_S(r, v))) > \mu / (\lambda' - \lambda)$,
Find the next vertex w minimize $\text{dist}(w, C_S(r, v))$ and set
 $r = r + \text{dist}(w, C_S(r, v))$.

$$r \in [\lambda, \lambda')$$

$$\text{cost}(\partial(C_S(r, v))) \leq \frac{\text{vol}(C_S(r, v))}{\lambda' - \lambda} \max \left[1, \log_2 \frac{m}{\text{vol}(E(C_S(r, v)))} \right]$$

Star Decomposition

Final Algorithm

$(\{V_0, \dots, V_k\}, \mathbf{x}, \mathbf{y}) = \text{StarDecomp}(G, x_0, \delta, \epsilon)$

1. Set $\rho = \text{rad}_G(x_0)$; $r_0 = \text{BallCut}(G, x_0, \rho, \delta)$ and $V_0 = B(r_0, x_0)$.
2. Let $S = BS(r_0, x_0)$;
3. Set $G' = (V', E', w') = G(V - V_0)$.
4. Set $(\{V_1, \dots, V_k, \mathbf{x}\}) = \text{ConeDecomp}(G', S, \epsilon\rho/2)$;
5. For each $i \in [1 : k]$, set y_k to be a vertex in V_0 such that $(x_k, v_k) \in E$ and y_k is on a shortest path from x_0 to x_k

$(\{V_1, \dots, V_k, \mathbf{x}\}) = \text{ConeDecomp}(G, S, \Delta)$

1. Set $G_0 = G, S_0 = S, k = 0$.
2. While S_k is not empty
 - (a) $k = k + 1; x_k \in S_k; r_k = \text{ConeCut}(G_{k-1}, x_k, 0, \Delta, S_{k-1})$.
 - (b) Set $V_k = C_{S_{k-1}}(r_k, x_k); G_k = G(V - \cup_{i=1}^k V_i), S_k = S_{k-1} - V_k$.
3. Set $\mathbf{x} = (x_1, \dots, x_k)$.

Star Decomposition

□ Cost

$$\text{cost}(\partial(V_0)) > \frac{3(\text{vol}(V_0) + 1) \log_2(|E| + 1)}{\rho}$$

$$\text{cost}(E(V_j, V - \cup_{i=0}^j V_i)) \leq \frac{2(1 + \text{vol}(V_j)) \log_2(m + 1)}{\epsilon \rho}$$

$$\begin{aligned} \text{cost}(\partial(V_0, \dots, V_K)) &\leq \sum_{j=0}^k \text{cost}(E(V_j, V - \cup_{i=0}^j V_i)) \\ &\leq \frac{2 \log_2(m + 1)}{\epsilon \rho} \sum_{j=0}^k (\text{vol}(V_j) + 1) \\ &\leq \frac{6m \log_2(m + 1)}{\epsilon \rho} \end{aligned}$$